



Plasma II (PHYS-424)

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**Based on lecture notes by
Prof. A. Fasoli, Prof. I. Furno,
Dr. A. Howling and Dr. D. Testa**

Spring Semester 2025

- None

Reminder

Go to <https://moodle.epfl.ch/course/view.php?id=14996> for links to notes and exercises

Plasma II

L3: Magnetohydrodynamic equilibrium configurations

H. Reimerdes

Based on the lectures
notes by D. Testa

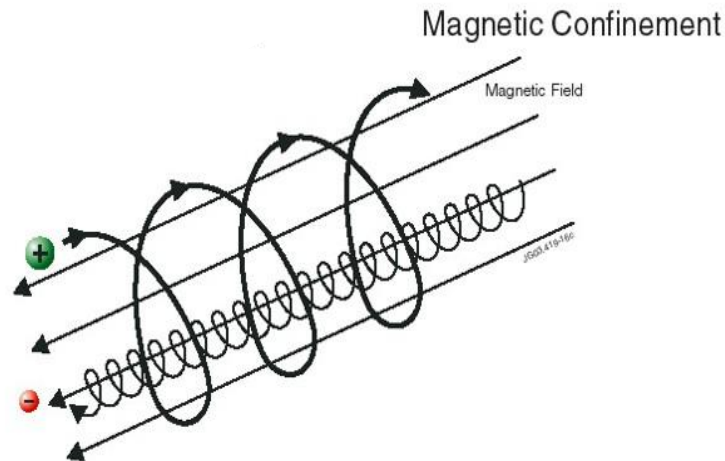
- L2: The Magnetohydrodynamic (MHD) description of a plasma
- L3: MHD equilibrium configurations of interest for magnetic confinement fusion
- L4: MHD stability and operational limits

Plasma confinement schemes for magnetic fusion

- To produce fusion in D-T plasmas we need

$$n\tau_E \sim 10^{20} \text{m}^{-3}\text{s} \quad \text{and} \quad T \geq 10 \text{keV}$$

for break-even



- Distinguish two types of magnetic confinement schemes
 - Plasma confinement in **linear** devices → open-ended
 - Plasma confinement in **toroidal** devices ← closed-field lines

MHD equilibrium configurations

Outline

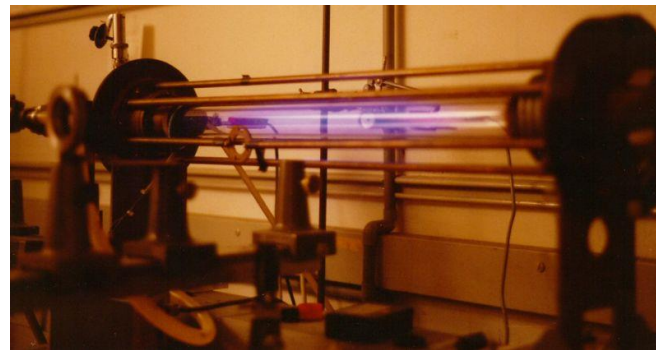
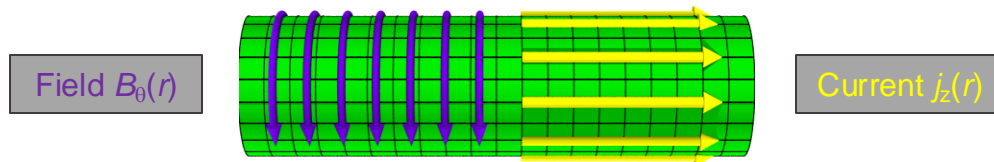
- Linear configurations
- Toroidally symmetric configurations
 - MHD equilibrium in 2-D configurations
 - The tokamak concept
- General toroidal configurations
 - The stellarator concept

See also

- EPFL MOOC “Plasma physics: Applications”, modules 7a,b
 - https://learning.edx.org/course/course-v1:EPFLx+PlasmaApplicationX+1T_2018/home
- Wesson, *Tokamaks* - Third Edition, Ch. 3.2-3.3, 3.9-3.12
- Freidberg, *Plasma Physics and Controlled Fusion*, Ch. 11.7

Linear confinement schemes: the Z-pinch

- **Z-pinch devices:** A magnetic configuration that confines a plasma using an axial current $j_Z(r)$ and a poloidal magnetic field $B_\theta(r)$ (see also L2)
 - The **ZETA** device (UK) was the first ever experiment to report fusion in 1957
 - The magnetic configuration of a Z-pinch can produce relaxed configuration states with $\tau_E > 1\text{ms}$
 - The Z-pinch is still used as a development path for inertial confinement

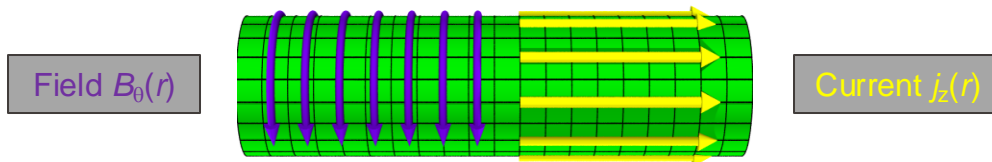


1D equilibrium

$$\frac{d}{dr} \left[p(r) + \frac{B_\theta^2(r)}{2\mu_0} \right] + \frac{B_\theta^2(r)}{\mu_0 r} = 0$$

Linear confinement schemes: the Z-pinch

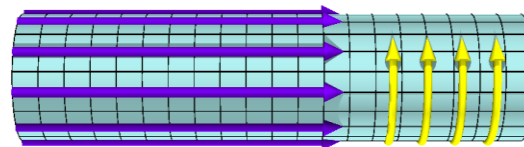
- **World's largest Z-pinch device:** Z-machine at Sandia National Laboratory
 - Current: up to 25MA
 - Electrical power up to 80TW
 - World's largest X-ray source with 350TW (3MJ)



Linear confinement schemes: the θ -pinch

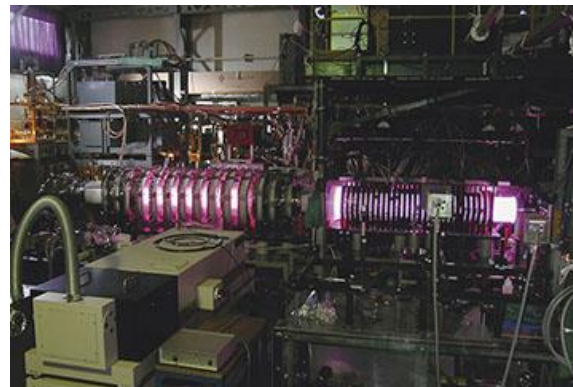
- **θ -pinch devices**: A magnetic configuration that tries to achieve confinement of the plasma using a poloidal current $j_\theta(r)$ and an axial magnetic field $B_z(r)$ (see also L2)

- Still used as a development path for inertial confinement

Field $B_z(r)$ Current $j_\theta(r)$

1D equilibrium

$$\frac{B_z^2(r)}{2\mu_0} + p(r) = \frac{B_z^2(a)}{2\mu_0}$$

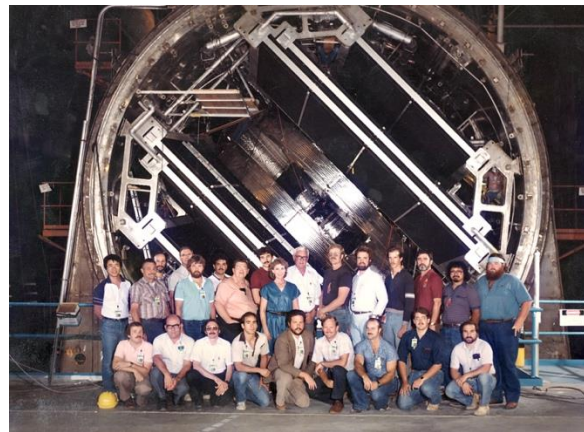
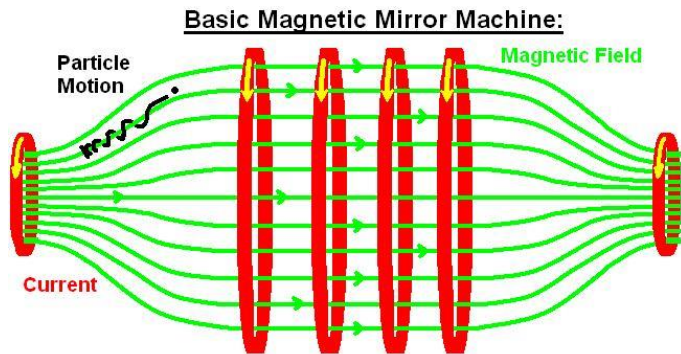


Theta pinch at Nihon University, Japan

Linear confinement schemes: mirror devices

■ Magnetic mirror devices (2D) → E3-1

- Charged particle can be reflected from a high magnetic field region to a low magnetic field region
 - This **mirror effect** only occurs for particles within a limited range of velocities

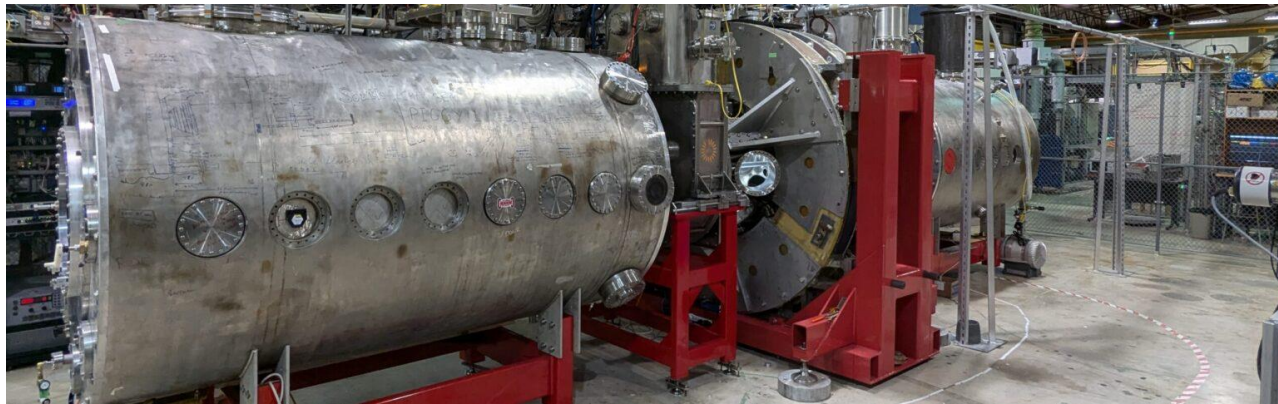


- The largest mirror device ever built was the **Mirror Fusion Test Facility** in 1986

Linear confinement schemes: mirror devices

■ Magnetic mirror devices (2D) → E3-1

- Charged particle can be reflected from a high magnetic field region to a low magnetic field region
 - This **mirror effect** only occurs for particles within a limited range of velocities



- Wisconsin HTS Axisymmetric Mirror (WHAM) will revisit concept using state-of-the-art high-temperature superconductor (HTS) technology with field up to 17T

Magnetic confinement in linear devices: summary

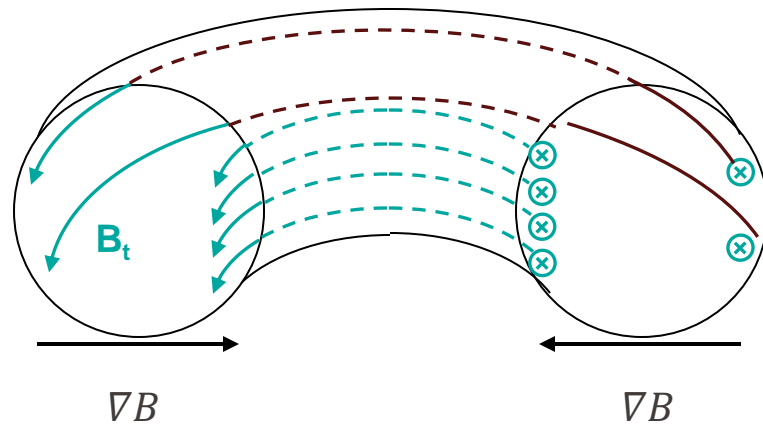
- Early research experiments, simple to build
- Examples: mirror devices and pinches
- Generally very poor confinement due to losses along field lines and different classes of MHD instabilities (→ L4)
- Still used for inertial confinement experiments
- Mirror re-visited using new coil technology

Outline

- Linear configurations
- **Toroidally symmetric configurations**
 - **MHD equilibrium in 2-D configurations**
 - The tokamak concept
- General toroidal configurations
 - The stellarator concept

Reminder: Closed field line configuration must have torus topology

- *Poincare theorem*: the only smooth 2D surface on which field lines can be covered by a **non-vanishing** vector field is a **torus** (\rightarrow L2)
- Consider a **toroidal field only** (toroidal theta pinch)



➤ $1/R$ dependence of B_ϕ causes $\nabla|\bar{B}|$

Magnetic field inhomogeneities lead to particle drifts (→ Introduction to Plasma Physics)

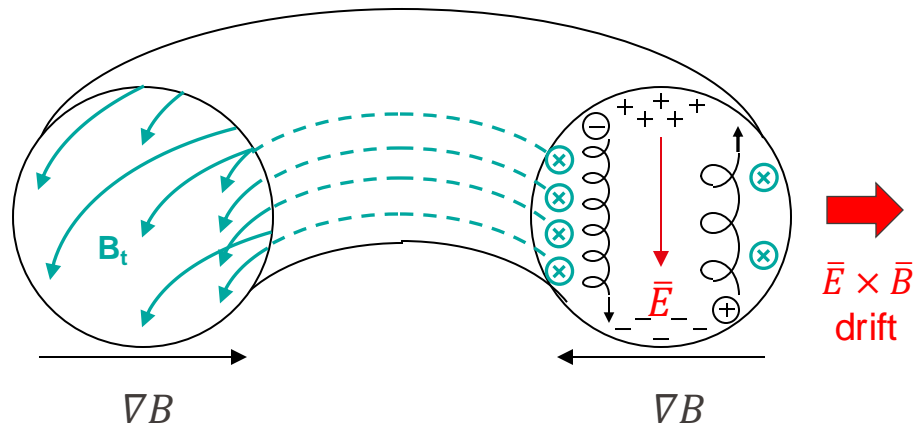
- Reminder: Guiding centre drifts (single particle picture)
 - Trajectory of charged particles in a magnetic field on time scales $\gg \tau_c$

Particle drifts in a purely toroidal field

1. $\nabla|\bar{B}|$ and **curvature drifts** with opposite signs for ions and electrons
 \rightarrow **charge separation**

2. Charge separation creates **vertical electric field \bar{E}**

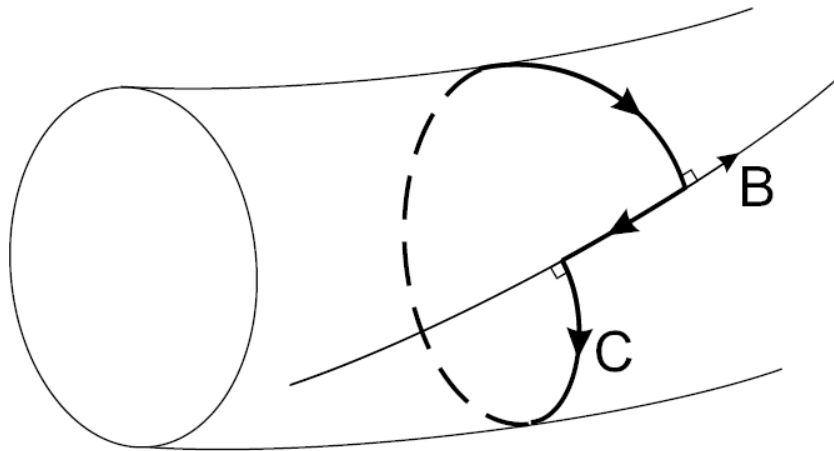
3. $\bar{E} \times \bar{B}$ drift leads to a collective **outward motion** of ions and electrons



- Confinement cannot be achieved in a pure toroidal field
- Add **poloidal field** (i.e. rotational transform) \rightarrow particles sample regions with opposite drifts and avoid charge separation

Specific case: Toroidally symmetric configuration

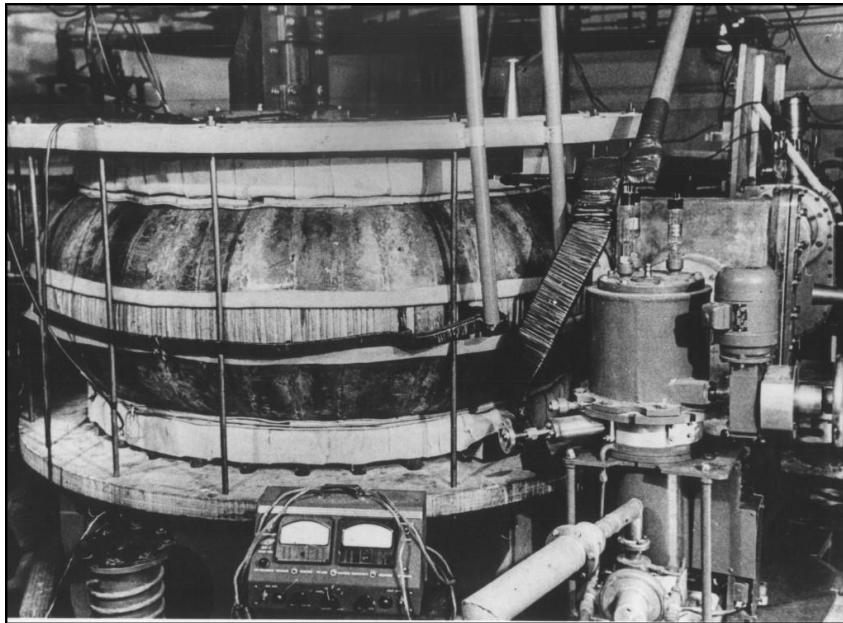
- Toroidal axisymmetric (2D) configuration with rotational transform (tokamak)



[Figure: P. Helander, EPFL seminar, 13.5.2019]

The tokamak configuration

- The tokamak (Russian acronym for ***T**oroidal**naya** **K**amera i **M**agnit**naya** **K**atus**h**ka* — toroidal chamber and magnetic coils)

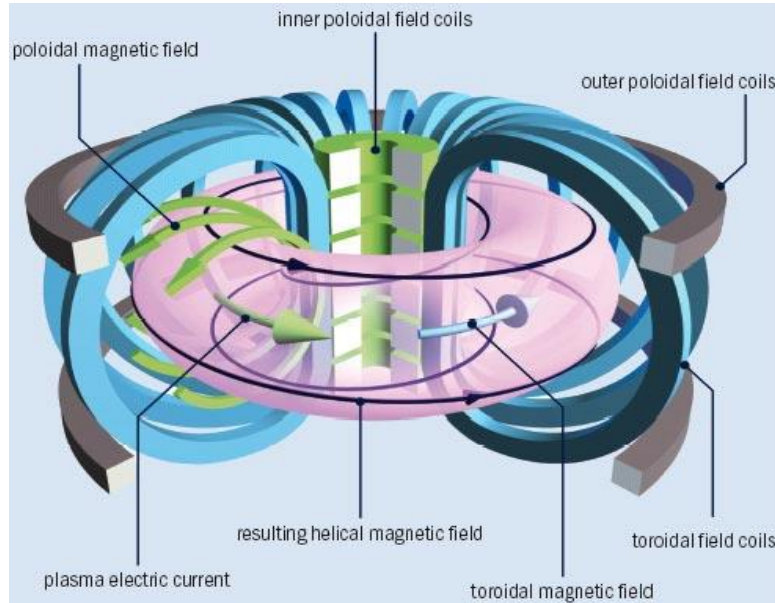


‘1958 configuration’
presented at the 2nd UN
International Conference on
the Peaceful uses of Atomic
Energy, Geneva
→ later named T1 tokamak

<https://www.iter.org/newsline/55/1194>

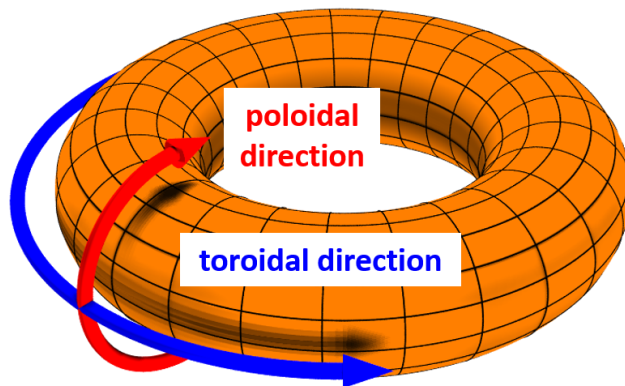
The tokamak configuration

- The tokamak (Russian acronym for ***T**oroidalnaya **K**amera i **M**agnitnaya **K**atushka* — toroidal chamber and magnetic coils)



Reminder: Toroidal geometry

- A **Torus**, a cylinder with its ends folded-up, has two preferential directions
 - The **toroidal direction** (ϕ): the longitudinal axis of the original cylinder, defining a possible symmetry axis
 - The **poloidal direction** (θ): defines the plane perpendicular to the longitudinal axis of the *original* cylinder



Def.: *Aspect ratio*

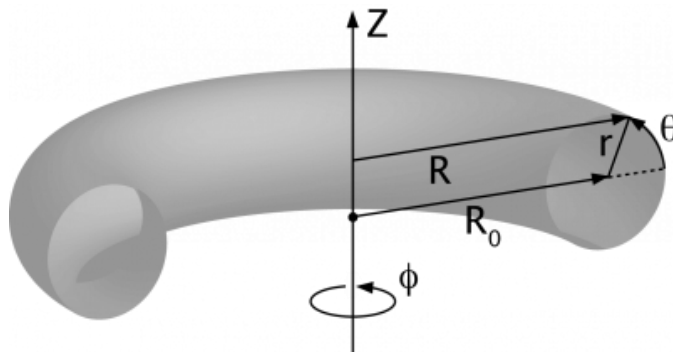
$$A \equiv \frac{\text{major radius}}{\text{minor radius}} = \frac{R_0}{a}$$

Image Credits: Creative Commons

Toroidally symmetric equilibrium

- Specific case of a multi-dimensional MHD equilibrium discussed in this lecture: the **toroidal axisymmetric (2D) equilibrium** (tokamak equilibrium)
- How to obtain the static ($\bar{V}(\bar{x}, t) = 0$) equilibrium ($\partial/\partial t = 0$)?
 1. Use **Gauss law** $\nabla \cdot \bar{B} = 0$ and **symmetry** to constrain \bar{B} components
 2. Use **Ampère's law** $\mu_0 \bar{j} = \nabla \times \bar{B}$ to link components of \bar{j} and \bar{B}
 3. Replace \bar{j} in **MHD force balance** $\nabla p = \bar{j} \times \bar{B}$

- Use *cylindrical coordinates* $\{R, \phi, Z\}$
 - Note: Distinguish from *toroidal coordinates* $\{r, \theta, \phi\}$



- Major simplification: **toroidal axisymmetric equilibrium**

$$\rightarrow \partial / \partial \phi = 0$$

for all equilibrium quantities

Axisymmetric 2D MHD equilibrium: Flux function

- Assume toroidal symmetry $\partial/\partial\phi = 0$

- No ϕ -dependence of equilibrium quantities including magnetic field

$$\bar{B} = (B_R(R, Z), B_\phi(R, Z), B_Z(R, Z))$$

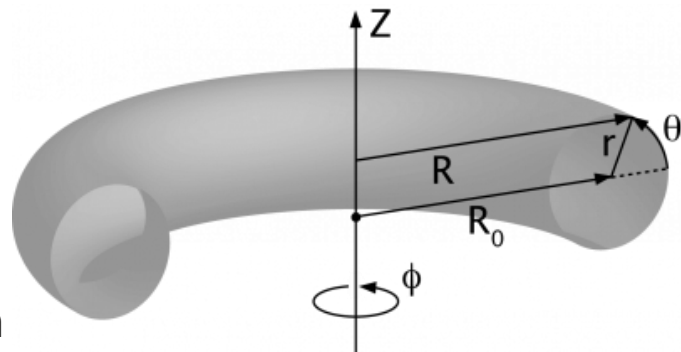
- Divergence-free fields (such as \bar{B}) can be derived from a vector potential

$$\bar{B} = \nabla \times \bar{A}$$

- Using $\partial/\partial\phi = 0$

$$B_R = -\frac{\partial A_\phi}{\partial Z}$$

$$B_Z = \frac{1}{R} \frac{\partial (RA_\phi)}{\partial R}$$



- Introduce flux function $\psi = RA_\phi$

$$B_R = -\frac{1}{R} \frac{\partial \psi(R, Z)}{\partial Z}$$

$$B_Z = \frac{1}{R} \frac{\partial \psi(R, Z)}{\partial R}$$

Axisymmetric 2D MHD equilibrium: Flux function

- Note that $(\bar{\mathbf{B}} \cdot \nabla)\psi = 0$, i.e. ψ is constant along magnetic field lines



→ Use $\psi(R, Z)$ to label flux surfaces

Axisymmetric 2D MHD equilibrium: Flux function

- Relate flux function ψ to **poloidal flux** ψ_p

$$\begin{aligned}\psi_p(R, Z) &\equiv \int_{S(R, Z)} \bar{B} \cdot d\bar{S} = \int_{S(R, Z)} \nabla \times \bar{A} \cdot d\bar{S} \\ &= \int_{\partial S(R, Z)} \bar{A} \cdot d\bar{l} = 2\pi R A_\phi(R, Z) = 2\pi\psi(R, Z)\end{aligned}$$

Def.: Poloidal flux

Axisymmetric 2D MHD equilibrium:

Force balance

2. Use Ampere's law $\mu_0 \bar{j} = \nabla \times \bar{B}$ to link \bar{j} and \bar{B} (assuming axisymmetry)

$$\begin{aligned} \mu_0 j_R &= -\frac{\partial B_\phi}{\partial Z} \quad , \quad \mu_0 j_\phi = \frac{\partial B_R}{\partial Z} - \frac{\partial B_Z}{\partial R} \quad , \quad \mu_0 j_Z = \frac{1}{R} \frac{\partial(RB_\phi)}{\partial R} \\ &= -\frac{1}{R} \frac{\partial^2 \psi}{\partial Z^2} + \frac{1}{R^2} \frac{\partial \psi}{\partial R} - \frac{1}{R} \frac{\partial^2 \psi}{\partial R^2} = -\frac{1}{R} \Delta^* \psi \end{aligned}$$

3. Substitute \bar{j} in force-balance $\nabla p - \bar{j} \times \bar{B} = 0$

$$R: \quad \mu_0 \frac{\partial p}{\partial R} + \frac{B_\phi}{R} \frac{\partial(RB_\phi)}{\partial R} + \frac{1}{R^2} \frac{\partial \psi}{\partial R} \Delta^* \psi = 0$$

$$\phi: \quad \frac{\partial \psi}{\partial R} \frac{\partial(RB_\phi)}{\partial Z} - \frac{\partial \psi}{\partial Z} \frac{\partial(RB_\phi)}{\partial R} = 0$$

$$Z: \quad \mu_0 \frac{\partial p}{\partial Z} + B_\phi \frac{\partial B_\phi}{\partial Z} + \frac{1}{R^2} \frac{\partial \psi}{\partial Z} \Delta^* \psi = 0$$

Axisymmetric 2D MHD equilibrium: Grad-Shafranov equation

3. Substitute \bar{j} in force-balance $\nabla p - \bar{j} \times \bar{B} = 0$

$$R: \quad \mu_0 \frac{\partial p}{\partial R} + \frac{B_\phi}{R} \frac{\partial(RB_\phi)}{\partial R} + \frac{1}{R^2} \frac{\partial \psi}{\partial R} \Delta^* \psi = 0$$

$$\phi: \quad \frac{\partial \psi}{\partial R} \frac{\partial(RB_\phi)}{\partial Z} - \frac{\partial \psi}{\partial Z} \frac{\partial(RB_\phi)}{\partial R} = 0$$

$$Z: \quad \mu_0 \frac{\partial p}{\partial Z} + B_\phi \frac{\partial B_\phi}{\partial Z} + \frac{1}{R^2} \frac{\partial \psi}{\partial Z} \Delta^* \psi = 0$$



$$\nabla \psi \times \nabla(RB_\phi) = 0$$



RB_ϕ constant on flux surfaces
 \rightarrow Introduce $F(\psi) = RB_\phi$

■ Use that p and F are flux functions

$$\mu_0 R^2 \frac{\partial p}{\partial \psi} + F \frac{\partial F}{\partial \psi} + \Delta^* \psi = 0$$

Grad-Shafranov equation

Axisymmetric 2D MHD equilibrium: Grad-Shafranov equation (cont.)

- The **Grad-Shafranov** equation for flux function $\psi(R, Z)$

$$\Delta^* \psi(R, Z) = -\mu_0 R^2 \frac{\partial p(\psi(R, Z))}{\partial \psi} - F(\psi(R, Z)) \frac{\partial F(\psi(R, Z))}{\partial \psi}$$

- with $\Delta^* \psi = \frac{\partial^2 \psi}{\partial R^2} - \frac{1}{R} \frac{\partial \psi}{\partial R} + \frac{\partial^2 \psi}{\partial Z^2}$

and $\Delta^* \psi = -\mu_0 R j_\phi$

- Short-hand: $\Delta^* \psi = -\mu_0 R^2 p' - FF'$

Grad-Shafranov equation: solution

- The solution $\psi(R, Z)$, $p'(\psi)$, $FF'(\psi)$ of the **Grad-Shafranov equation** for 2D axisymmetric toroidal systems provides:
 - Magnetic field as a function of R and Z
 - toroidal component: $B_\phi(R, Z) = F(\psi(R, Z))/R$
 - poloidal components: $B_R(R, Z) = -(1/R) \partial\psi(R, Z)/\partial Z$
 $B_Z(R, Z) = (1/R) \partial\psi(R, Z)/\partial R$
- Plasma pressure $p(R, Z) = p(\psi(R, Z))$
- Plasma current density
 - toroidal component: $j_\phi(R, Z) = -1/(R\mu_0) \Delta^* \psi(R, Z)$
 $= Rp'(\psi(R, Z)) + FF'(\psi(R, Z))/(\mu_0 R)$

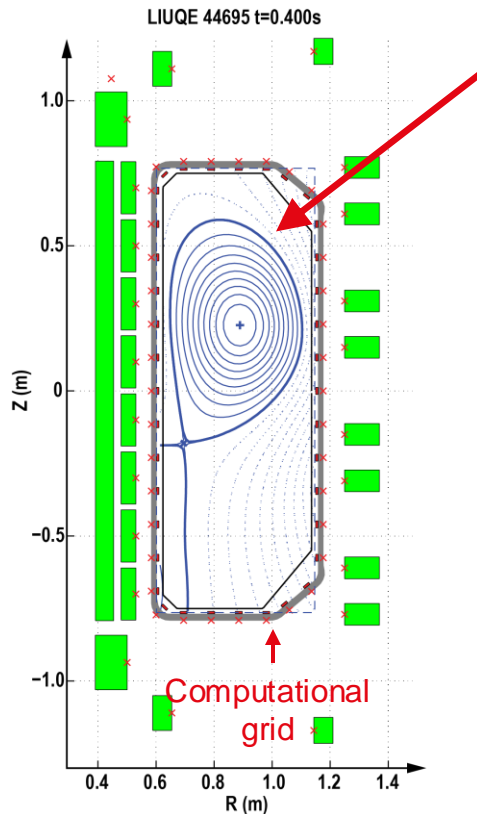
How to obtain solutions of the Grad-Shafranov equation

Example

Input

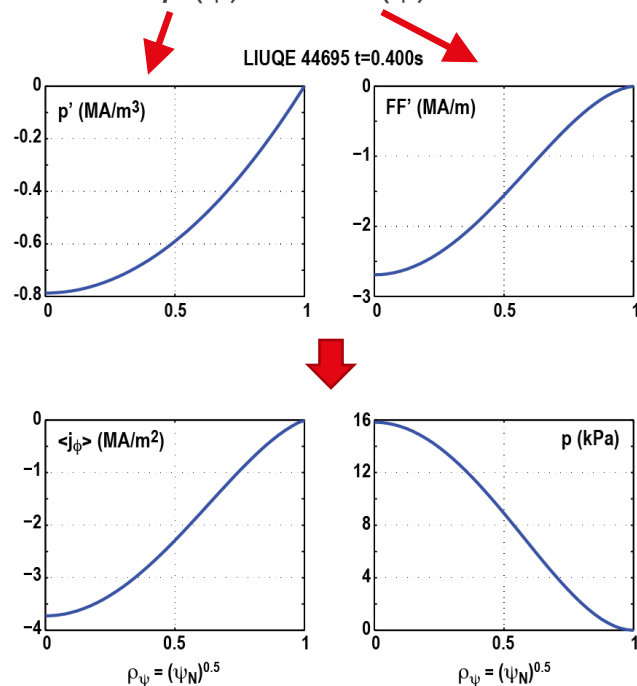
Coil current
measurements

Magnetic
measurements
of flux and
poloidal field



Equilibrium solver yields

- Flux contours $\psi(R, Z)$
- Profiles $p'(\psi)$ and $FF'(\psi)$



2-dimensional MHD equilibrium: summary

- Toroidicity introduces particle drifts that must be averaged out by poloidal transits (**rotational transform**)
- Toroidally symmetric tokamak requires a **plasma current** for rotational transform
- Determination of a 2-dimensional magnetic equilibrium: performed with the **Grad-Shafranov equation**
- Equilibrium calculated in terms of two prescribed functions $F(\psi)$ and $p(\psi)$ of the magnetic flux $\psi(R,Z)$

Outline

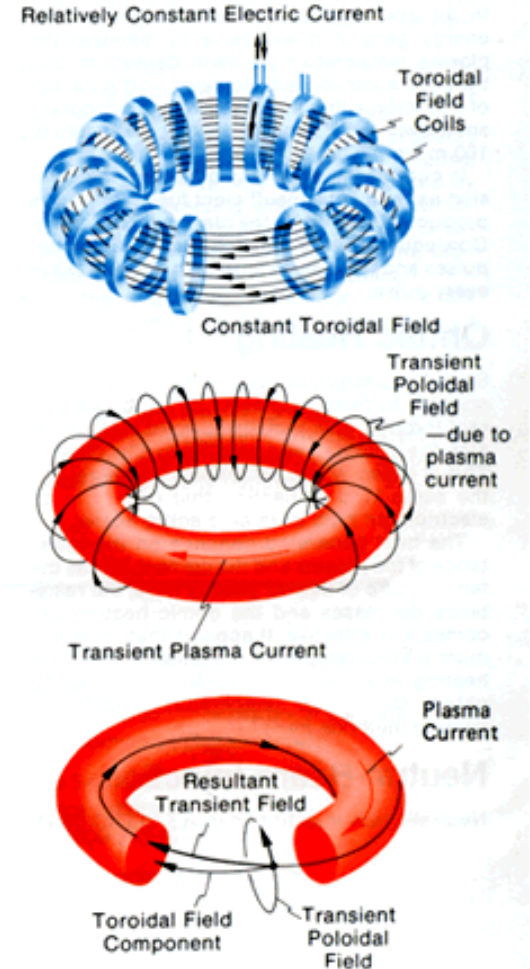
- Linear configurations
- **Toroidally symmetric configurations**
 - MHD equilibrium in 2-D configurations
 - **The tokamak concept**
- General toroidal configurations
 - The stellarator concept

The tokamak concept

- Plasma confinement in **toroidal** magnetic fusion devices: the **tokamak**
 - Magnetic field components
 - Plasma current
 - Flux-surfaces
 - Plasma shaping
 - The safety factor
 - Typical equilibrium profiles

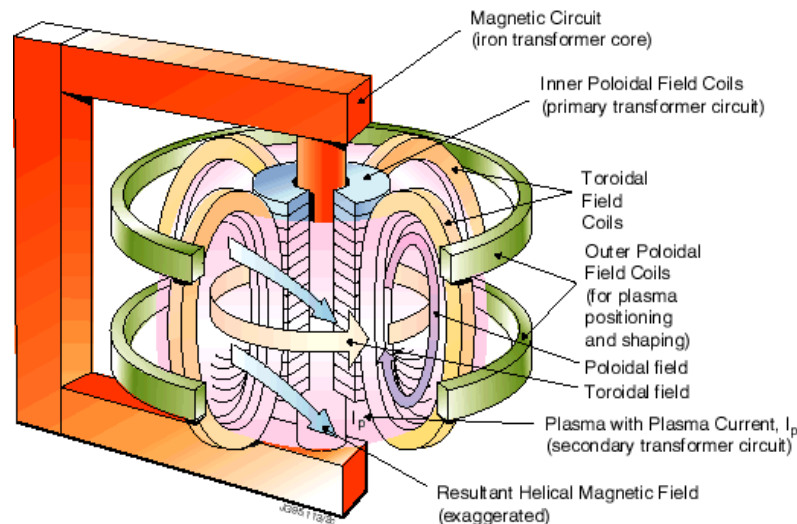
The tokamak concept

- **Tokamak**: superposition of different magnetic fields encloses plasma
 - **Toroidal field**: main component, produced by external coils
 - **Poloidal field**: generated by inducing a current in the plasma along the toroidal direction
- Helical field lines



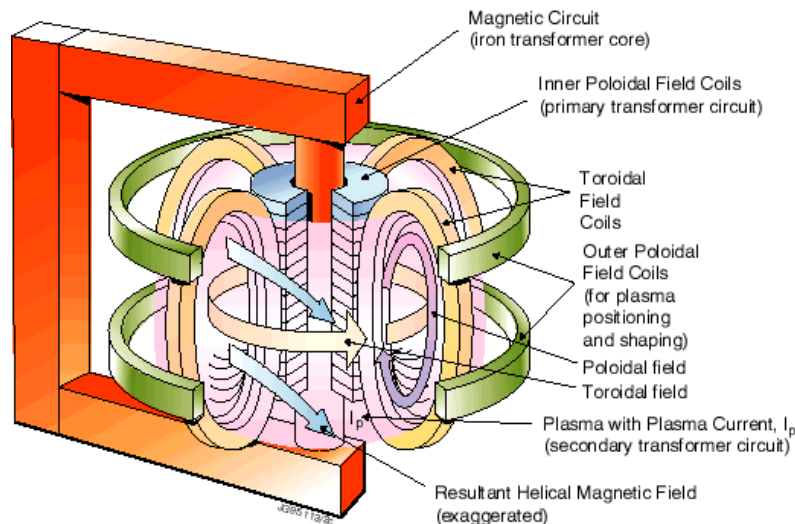
The tokamak device: TF coils

- The **toroidal magnetic field** (TF) is the **dominant** magnetic field component
- Toroidal field has a $1/R$ dependence
 - TF higher close to inner coil leg: this is the **high-field side** of the tokamak
 - TF lower close to outer coil leg: this is the **low-field side** of the tokamak



The tokamak device: ohmic transformer

- **Plasma current:** driven by a toroidal electric field induced by transformer action
 - Poloidal flux change in the chamber due to a current ramp in the inner poloidal field (PF) coils induces loop voltage
 - These coils act as the primary of a transformer circuit with the plasma being the secondary
 - Iron core often used for the inner PF coils to reduce power supply requirements



- **Toroidicity** introduces 3 outward directed forces
 - a) **Hoop force**: Created by a toroidal current and a poloidal field
 - Stronger poloidal field on the inside leads to a net outward $\vec{j} \times \vec{B}$ force
 - Analogous to outward expansion of a current carry wire loop
 - b) **Tire tube force**: Created by the plasma pressure
 - Larger surface area S on the outside of an isobaric surface than on its inside leads to a net outward force
 - Analogous to larger tension on the outside of an inflated inner tube
 - c) **$1/R$ force**: Created by the $1/R$ decay of the toroidal field in the presence of poloidal currents
 - Diamagnetic* poloidal current (resulting from ∇p) leads to a larger outward force on the inside than the inward force on the outside

*when plasma pressure sufficiently high

The tokamak device: vertical field coils

- Exert a radial force by **applying** a vertical field

- Requires vertical field coils
- Choose direction and magnitude for $j_\phi \times B_V$ to balance outward forces

- Simple model yields

[J. Freidberg, PP and FE, Chapter 11.7.7]

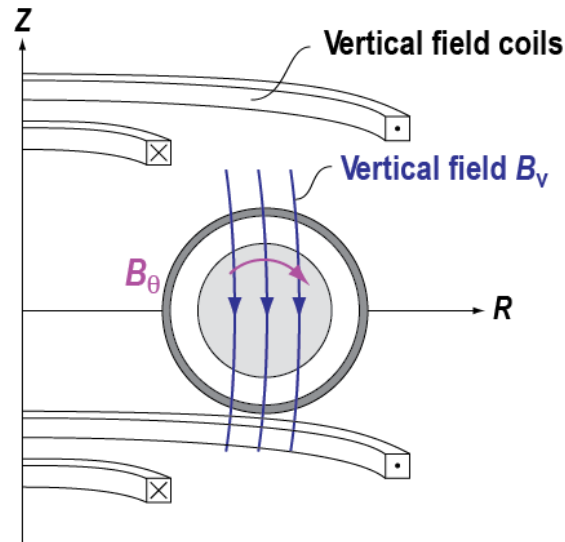
$$\frac{B_V}{B_{\theta,a}} \approx \frac{1}{4} \frac{a}{R_0} \left[\underbrace{l_i + l_e + 2}_{\text{Hoop force}} + \underbrace{\frac{2\mu_0 \langle p \rangle}{B_{\theta,a}^2}}_{\text{Tire tube force}} + \underbrace{\frac{B_{\phi,a}^2 - \langle B_\phi^2 \rangle}{B_{\theta,a}^2}}_{1/R \text{ force}} \right]$$

Inverse aspect
ratio ε

Hoop force

Tire tube
force

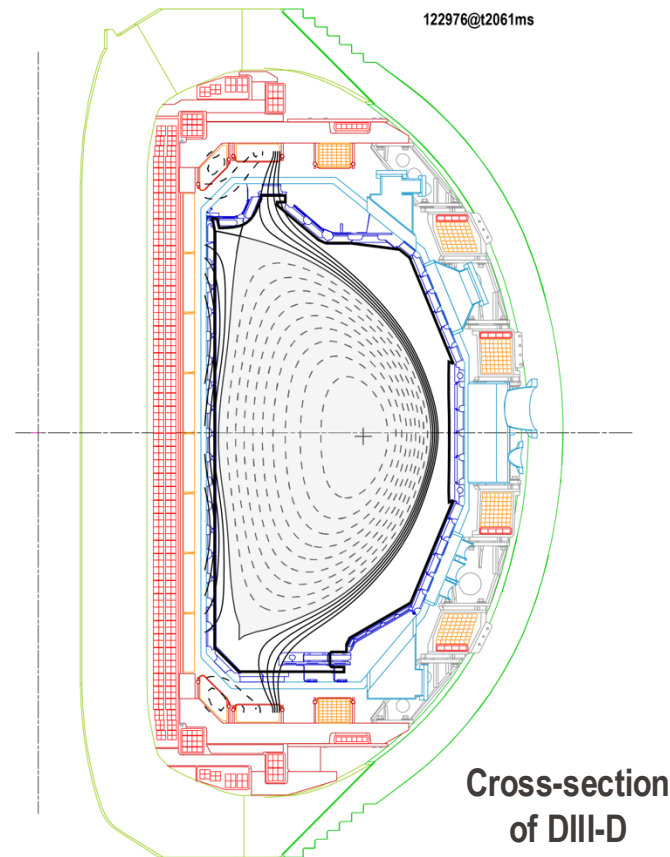
1/R force



[Figure adapted from J. Freidberg, PP and FE]

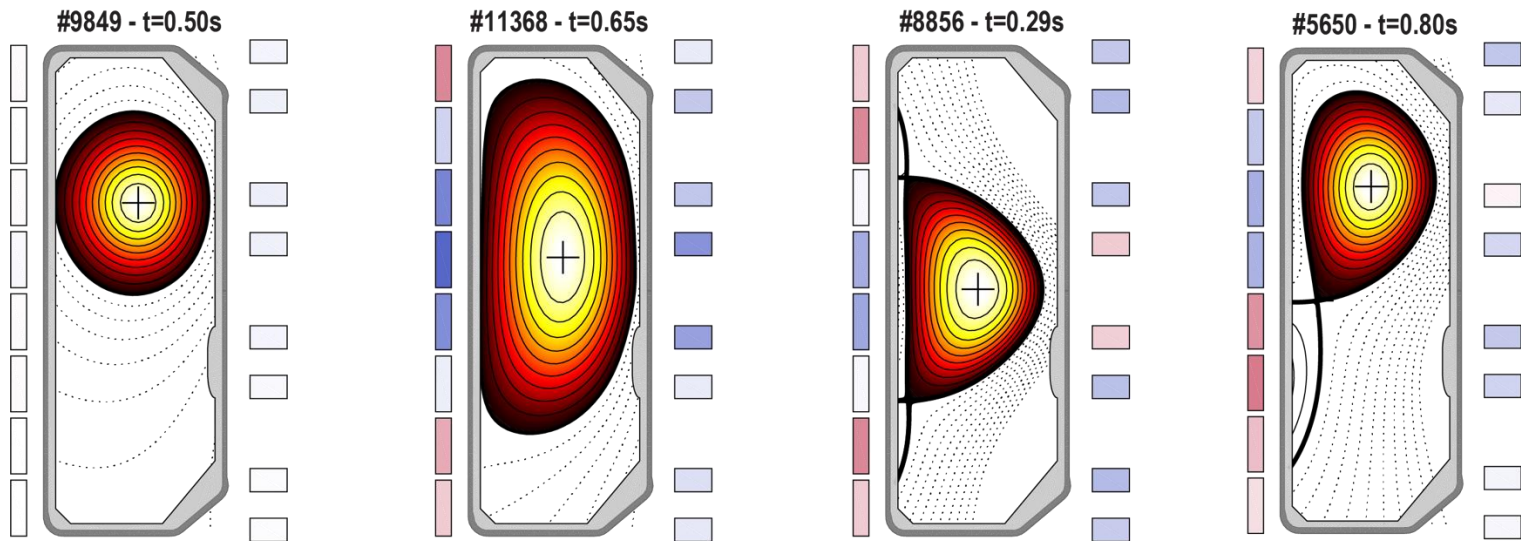
Flux-surface geometry: Shafranov shift

- **Flux-surfaces**: contours of constant- ψ in the poloidal plane
 - Flux surfaces form a set of nested contours
- **Magnetic axis** (R_{mag} , Z_{mag}): extremum of the flux
 - **Shafranov shift** Δ : outward shift of R_{mag} with respect to the geometric centre of the plasma
- Flux-surfaces more closely spaced on the LFS of the plasma



Flux surface geometry: plasma shaping

- Use **poloidal field coils** for plasma shaping



Circular

$$\kappa = 1.2$$

$$\delta = 0.0$$

Elongated

$$\kappa = 2.3$$

$$\delta = 0.3$$

Triangular

$$\kappa = 1.6$$

$$\delta = 0.8$$

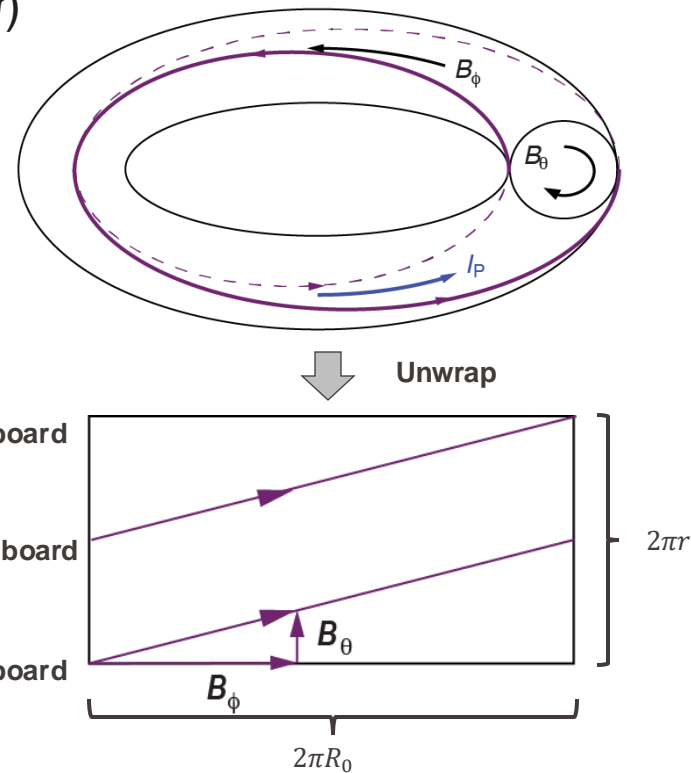
Diverted

**Cross-sections
of TCV**

Magnetic field line geometry

- **Safety factor:** defined as a flux-function $q(\psi)$
 - Consider large aspect ratio limit $R_0/a \gg 1$ and a circular plasma

Reminder: Safety factor



Magnetic field line geometry

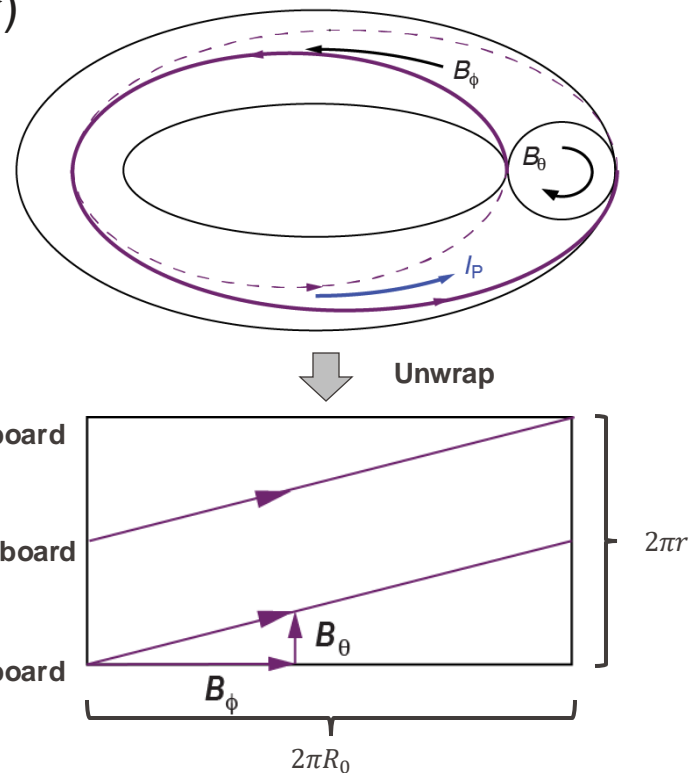
▪ **Safety factor**: defined as a flux-function $q(\psi)$

- Consider large aspect ratio limit $R_0/a \gg 1$ and a circular plasma

$$q(r) = \frac{rB_{\phi,0}}{R_0B_{\theta}(r)}$$

$$= \frac{2\pi r^2 B_{\phi,0}}{\mu_0 R_0 I(r)}$$

- Rational q -surfaces: $q_{\text{res}} = m/n$
- Perturbations can resonate with this natural periodicity of the equilibrium \rightarrow $q(r)$ defines plasma stability!

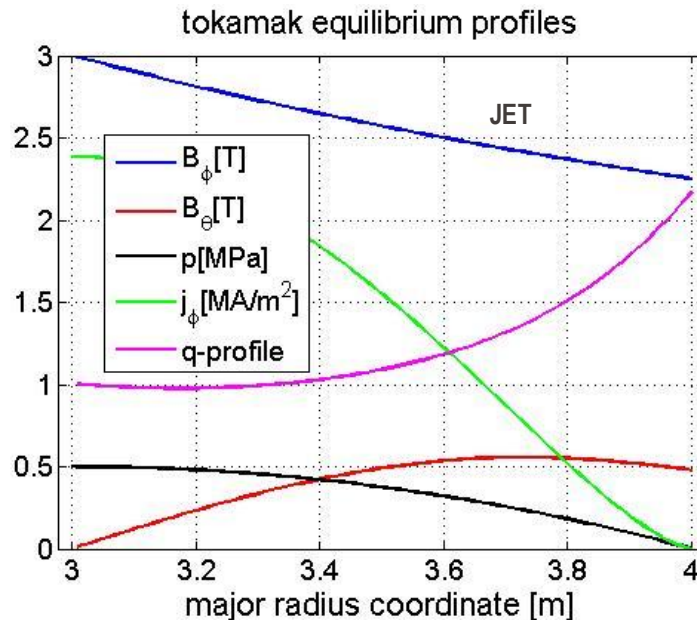


Typical equilibrium profiles

■ Tokamak equilibrium profiles:

2D axis-symmetric equilibrium

- Toroidal magnetic field $B_\phi(R) \propto 1/R$
- Poloidal magnetic field $B_\theta(R, Z)$ increases from the center, where $B_\theta(R_{\text{mag}})=0$, towards the edge
+ Typically $B_\theta/B_\phi \approx 0.1$
- Plasma pressure $p(\psi)$ peaks on the magnetic axis
- Toroidal current $j_\phi(R, Z)$ typically peaks on the magnetic axis
- Safety factor $q(\psi)$ typically increases from the magnetic axis towards the edge
+ Values depend on current profile and plasma shape (see E3-2)



The tokamak concept: summary

- Plasma current driven by a toroidal electric field usually induced by transformer action → intrinsically pulsed
- Toroidicity leads to outward forces that must be balanced by a vertical magnetic field
- Tokamak: superposition of various magnetic fields
 - Toroidal field: dominant component, generated by external coils
 - Poloidal field: generated by inducing a toroidal plasma current
 - Vertical field: generated by external coils
- Toroidal current j_ϕ and plasma pressure p typically peak on the magnetic axis

Outline

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Stellarator vs. Tokamak

- **Tokamak:** a 2D toroidal device

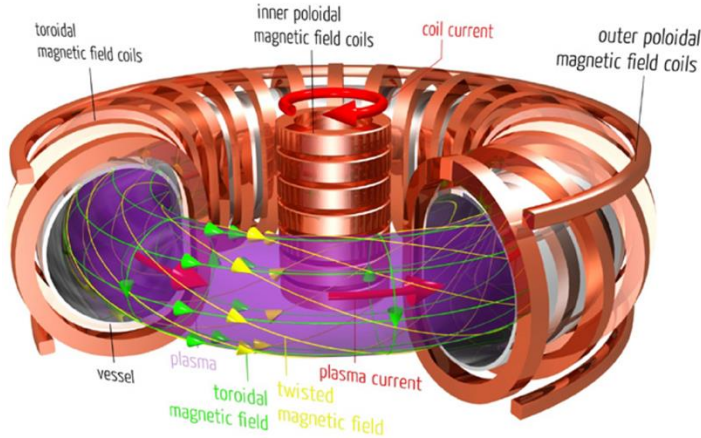


Image Credits: Max-Planck Institut für Plasmaphysik

- **Stellarator:** a 3D toroidal device

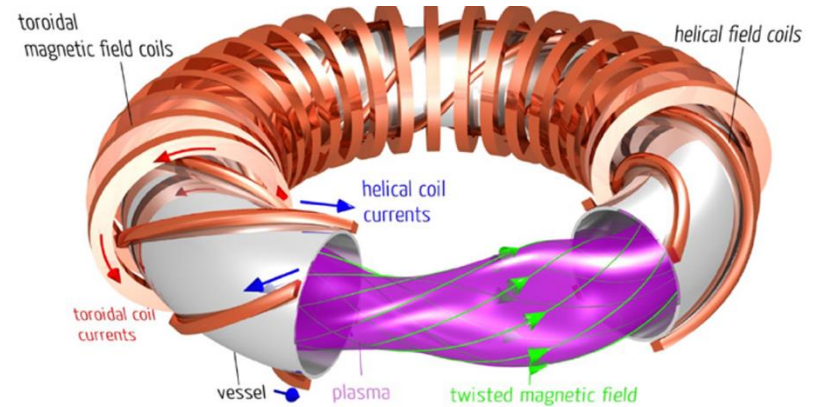
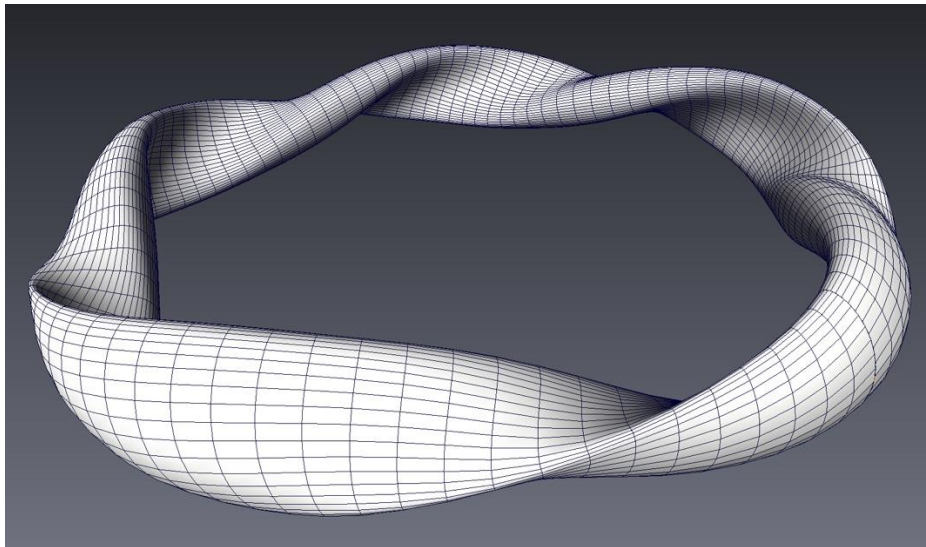


Image Credits: Max-Planck Institut für Plasmaphysik

Stellarator vs. Tokamak

- 3D geometry necessary to generate rotational transform without a plasma current



[Figure: P. Helander, EPFL seminar, 13.5.2019]

Stellarator vs. Tokamak

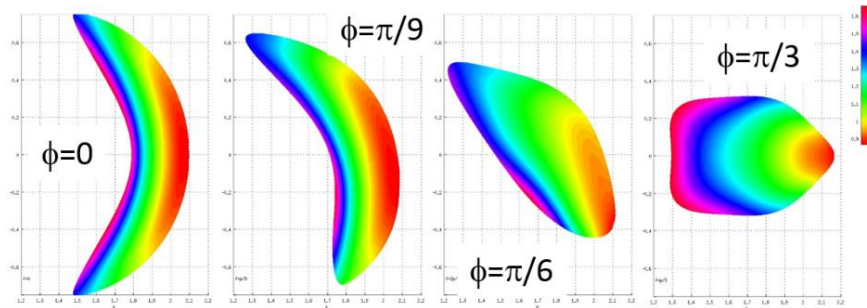
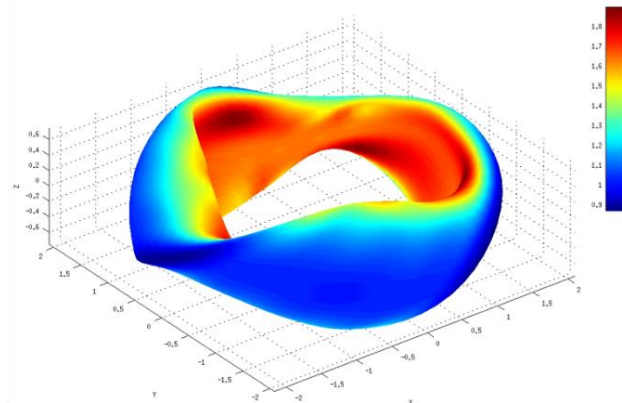
- **Stellarator**: no externally driven plasma current, plasma confinement solely due to the externally driven magnetic field components
- **Stellarator**: toroidal equilibrium is truly non-axisymmetric in 3D
→ all equilibrium quantities are also function of the toroidal angle ϕ
- **Tokamak**: a toroidal plasma current is used to produce a poloidal magnetic field and obtain rotational transform
- **Tokamaks**: axisymmetric system: $\partial/\partial\phi \equiv 0$ for all equilibrium quantities → 2D toroidal equilibrium!

- 3D equilibrium configurations are found using a variational approach
→ minimise the total energy of the system

$$W = \int \left(\frac{|\bar{B}|^2}{2\mu_0} + \frac{3}{2}p \right) dV$$

- It can be shown that in the 2D limit the variational approach is equivalent to solving the Grad-Shafranov equation

- **Example:** the NCSX stellarator

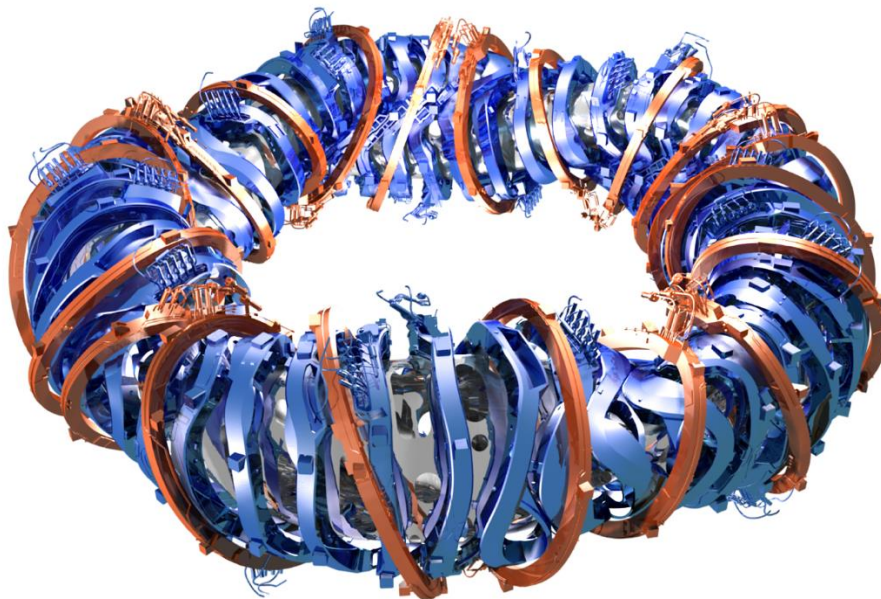


toroidal variation of equilibrium for the NCSX stellarator

Image Credits: Dr. W.A.Cooper, CRPP-EPFL

Toroidal confinement in the stellarator

- **Stellarator**: 3D magnetic field provided by **3D external coils**
 - With super-conducting magnets, magnetic field can (in principle) be maintained continuously

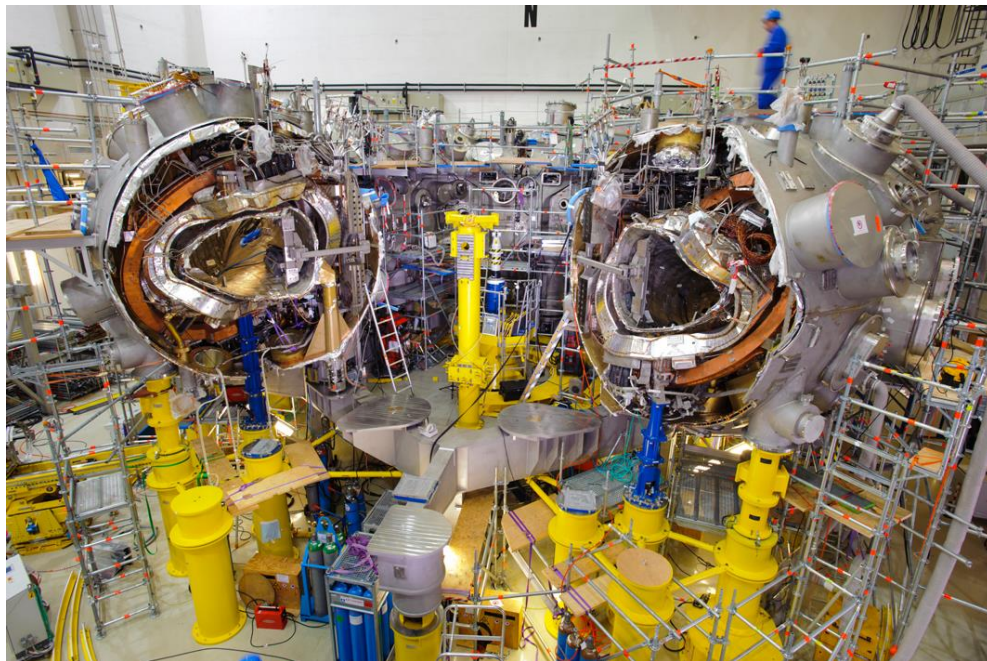


Toroidal confinement in the stellarator

- **Stellarator**: very complicated 3D shape for super-conducting coils
 - Magnetic field must be accurately tailored to prevent energetic particles from escaping

Wendelstein 7-X (IPP-Greifswald, Germany)

- Major radius: 5m
- Minor radius: 0.53m
- Volume: 30m³
- Magnetic field: 3T



Re-cap: Magnetohydrodynamic equilibrium configurations

- Toroidal (closed field line) configurations have superior confinement properties than linear (open ended) configurations
- Axisymmetric (2D) equilibria are described by the Grad-Shafranov equation
 - Pressure p and $F=RB_\phi$ are functions of the flux ψ
 - Need for an externally applied vertical field for toroidal force balance
- Tokamak components are toroidal field coils, inner poloidal field coils (primary of the transformer), vertical field coils (for equilibrium) and poloidal field coils (for shaping)
 - Induction of plasma current makes a tokamak intrinsically pulsed
- Stellarators generate the magnetic field (predominantly) with external coils
 - Stellarators are in principle capable for steady-state operation